

Determination of water saturation of oil reservoirs with the using of fuzzy logic method

Gulshen Mustafaeva

Abstract

Determination of water saturation is necessary to estimate the probability of producing a volume of oil for a given reservoir size. To obtain information about the technical condition of wells and successfully conduct development in conditions of inaccurate data, it is necessary to study the reservoir and filtration properties of reservoirs using the possibilities of fuzzy logic theory. Therefore, the paper considers a method that does not require all porosity values.

Key words: rock, porosity, logging, water saturation, cross-plot, fuzzy logic; fuzzy c-mean clustering

The development of oil fields requires knowledge of the nature and dynamics of well injectivity, including the possibility of maximum reservoir coverage with injected water. Injection into wells of fresh water from open reservoirs and effluents from oil fields leads to siltation of the filtration surface with introduced suspended solids, resins, oil products and salts. At the same time, there is a decrease and often a complete loss of reservoir injectivity and, ultimately, a decrease in oil production.

Insufficient reservoir coverage is observed due to the geological structure of the reservoir, heterogeneity, reservoir properties of rocks, namely: porosity, permeability, residual oil and water saturation of the reservoir. [1,2] In this regard, in order to increase the injectivity of productive rocks, it is of great importance to consider the distribution of water in the pores of the productive formation, which significantly affects the phase permeability of rocks for oil, water and gas, that is, the exploitation of oil and gas deposits is due to filtration huge masses of liquids in a porous medium, the properties of which determine the patterns of oil and water filtration, well flow rates, and reservoir productivity.

Water saturation characterized by both the wettability of rocks by displacing fluids, the intensity of capillary processes in the formation, and the amount of oil in the pore space of the formation. The water saturation value can be used to determine the likelihood of hydrocarbon production as well as to estimate the volume of oil for a given reservoir size. [3]

Nowdays uses a machine learning method, which is a class of artificial intelligence methods, the characteristic feature of which is not the direct solution of the problem, but learning through the application of solutions to many similar problems. [11] Alrumah and Ertekin have predicted water saturation around vertical and horizontal wells with the using an artificial neural network. The main advantage of neural network model is possibility to create modeling process which does not require the data that are often difficult to obtain in practise. Most currently in use process automation applications,

Fuzzy logic allows you to apply the experience of operators and process control technologists. But, the disadvantage of this model is the process is not available for other estimations. The development of a fuzzy rule base is interactive process. For the most part, this is a collection of knowledge and experience. One of the benefits of fuzzy logic is the ability to build a rule base approved specialists before checking its work in real conditions. The goal of this paper is to determine water saturation of the drilling process at various depths using a fuzzy system. Here, the water saturation prediction is based on the variables of depth. A method for determining the parameters of a fuzzy inference system is described the Takagi-Sugeno system. The properties that must satisfy both systems as universal approximators for their identity. An algorithm for the formation of membership functions of the right parts of the rules of the system is given Mamdani and the method of forming the system as a whole. Fuzzy rule formation uses fuzzy c-means clustering (FCM) and zero-order Sugeno fuzzy logic. The FCM method is used for determining the most optimal number of rules used in the setting of fuzzy rules.

Consider ways to measure water saturation. To characterize the water saturation of reservoir rocks, the water saturation coefficient S_w is used. The water saturation of a formation is defined as the ratio of the pore volume or the proportion of the pore space (Fig. 1) occupied by water to the total volume of the pore

space. To determine S_w , many other petrophysical parameters must be known, which can be obtained from well logging or laboratory core measurements. The total volume of water per unit volume of rock is the product of ϵS_w , and the total volume of hydrocarbons is $\epsilon(1 - S_w)$

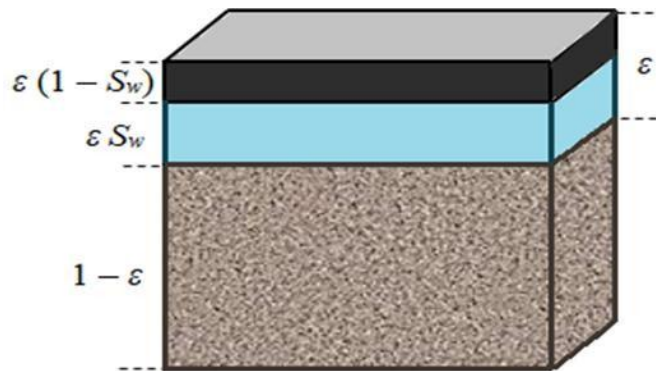


Figure1. Determination of water saturation of the rock.

Fuzzy Logic of Zero-Order Sugeno

Fuzzy logic inference systems clear predicate rules If ... Then . Every rule of thumb the (referred to the tors of the following). Sugeno fuzzy logic model is an approach to produce fuzzy rules from the applied input-output data. Zero-order Sugeno fuzzy logic is stated in the following formula. If x_1 is A_1 , ..., and x_n is A_n , then $z = b$ where (x_1, \dots, x_n) is the input of fuzzy logic, A_i is the fuzzy set on the i -th input, b is a real constant.

In contrast to some other types of fuzzy inference, fuzzy systems Takagi - Slowly generates clear numerical values. The most importantly, the following is a referral to the same, The following is the same In the consequent of the rules. The reference is being referred to the reference to the following The basis of the dependence between the blocks of fuzzy rules, allowing the construction The initialization of matrix $U = [u_{ij}]$, $U_{0 \text{ ii}}$. In the k -th step calculate the center of vector $C(k) = [c_j]$ with $U_k C_i = \sum u_{ij} m_{xj} n_{j=1} \sum u_{ij} n_{m j=1} (1)$ iii. Update U_k , $U(k+1)$ iv. $d_{ij} = \sqrt{\sum (x_i - c_i) n_{i=1}}$ a. $u_{ij} = 1 \sum (j) 2^{m-1} c_{k=1}$ v. If $|(k+1) - (k)| < \epsilon$ then, stop. Here after, the data were divided into 75% for training data and 25% for testing data. Furthermore, the input variables used in this study are depth, effective porosity, effective porosity of density-neutron log, total porosity, and total porosity of density-neutron log. The output variable of the fuzzy system is water saturation. The next step was the clustering process using FCM, which was followed by the fuzzification and processing of the fuzzification results data using the zero-order Sugeno fuzzy system.

The obtaining of the optimal cluster is provided through a try and error method to get the lowest MAPE value for training and testing data. The results are presented in Table 1.

Table 1. The results of error method

| Data | MAPE | Testing | Mean MAP |
|------|----------|---------|----------|
| | Training | | |
| 10 | 27.71424 | 29.1206 | 28.91746 |
| 11 | 24.94677 | 28.8411 | 28.89395 |
| 12 | 30.48908 | 27.639 | 27.56409 |
| .. | ... | ... | ... |

| | | | |
|-----|----------|---------|----------|
| 150 | 15.55787 | 15.2627 | 15.41031 |
| 151 | 14.16582 | 13.6453 | 13.90558 |
| 152 | 14.22539 | 14.1753 | 14.20036 |
| ... | ... | ... | ... |
| 481 | 10.98571 | 10.8308 | 10.90829 |
| 482 | 10.72528 | 10.5390 | 10.63216 |
| 483 | 10.93887 | 10.4922 | 10.71557 |
| 484 | 9.939734 | 9.34355 | 9.641644 |

After that, the obtained center was then used to create a zero-order Sugeno fuzzy rules with 3 fuzzy rules. The obtained center matrix can be seen in Table 2.

Table 2 The center of optimal cluster

| Clust | Depth | PHIE | PHIE_DN | PHIT | PHIT_DN | SWE |
|-------|-----------|-----------|-----------|-----------|-----------|-----------|
| 1 | 1570.6344 | 0.1575109 | 0.1575110 | 0.1575115 | 0.1575116 | 0.2079081 |
| 2 | 1665.3021 | 0.1753974 | 0.1753982 | 0.1754032 | 0.1754039 | 0.1768089 |
| 3 | 1456.9996 | 0.2009874 | 0.2009879 | 0.2010350 | 0.2010355 | 0.1890310 |

Based on Table 1, 3 optimal clusters are obtained and therefore there are zero-order Sugeno fuzzy rules which can be stated as follows:

“IF $x_1 = DEP_1$ and $x_2 = PHIE_1$ and $x_3 = PHIE_DN_1$ and $x_4 = PHIT_1$ and $x_5 = PHIT_DN_1$, THEN $y = b_1$ ”

“IF $x_1 = DEP_2$ and $x_2 = PHIE_2$ and $x_3 = PHIE_DN_2$ and $x_4 = PHIT_2$ and $x_5 = PHIT_DN_2$, THEN $y = b_2$ ”

“IF $x_1 = DEP_3$ and $x_2 = PHIE_3$ and $x_3 = PHIE_DN_3$ and $x_4 = PHIT_3$ and $x_5 = PHIT_DN_3$, THEN $y = b_3$ ”

Conclusion

In this research was done the prediction of water saturation. The method of fuzzy logic is proposed is the reality of the reference is the same of the following. Taking into account the hierarchy of blocks of fuzzy rules this method makes it possible to reduce the dependence of the result and input data. This method allows more unmistakable prediction results and create a transparent water saturation prediction process by describing it through fuzzy rules. In general, our results demonstrate that the proposed methods provide a reliable determination of the water saturation value S_w and the possibility of using them in the study of any carbonate or shale-sand reservoirs.

References

- [1] Rzaev Ab. G., Rasulov S.R., Ragimova S.N., Orudzhev V.V., Mustafayeva G.R. Razrabotka metoda otsenki sostoyaniya neftyanoy zalezhi. // Neftepromislovoye delo, 2015, No. 5, p. 21-23
- [2] Rasulov S.R., Kelbaliyev G.I., Rzaev Ab.G., Orudzhev V.V., Mustafayeva G.R. Uplotneniye neftyanoqo plasta v rezultate deformatsii i osajdeniya razlichnix primesey. // Vestnik Azerbaydjanskoj Injenernoy Akademii, 2015, No. 4, p. 101-112
- [3] Kelbaliyev G.I., Rzaev Ab. G., Rasulov S.R., Mustafayeva G.R. Problemi nelineynostey uravneniy

filtratsii neftey v poristix sredax. // Neftepromislovoye delo, 2015, No. 8, p.23-26

[4] Bhavsar, Parth, Ilya Safro, Nidhal Bouaynaya, Robi Polikar, and Dimah Dera. "Machine Learning in Transportation Data Analytics." *Data Analytics for Intelligent Transportation Systems* (2017): 283-307.

[5] Kenari, Seyed Ali Jafari, and Syamsiah Mashohor. "Robust committee machine for water saturation prediction." *Journal of Petroleum Science and Engineering* 104 (2013): 1-10. <https://doi.org/10.1016/j.petrol.2013.03.009>

[6] Alrumah Muhammad and Ertekin Turgay, "Prediction of the Water Saturation around Wells with Bottom Water Drive Using Artificial Neural Networks." *Journal of Petroleum and Gas Engineering* 10, no. 2 (2019): 14-22.